DISCIPLINE (ELECTRICAL ENGG.)	SEMETER – 6 th sem (2022-2023)	NAME OF THE FACULTY Er.Sushree Sangita Panda
SUBJECT:- CONTROL SYSTEM ENGINEERI NG	NO OF CLASS/WE EKS Allotted :5	SEMESTER FROM-14.02.2023 to 25.05.2023 No of weeks:15
WEEKS – 15	CLASS/DAY	Theory
14.02.2023 to 18.02.2023	1st	FUNDAMENTAL OF CONTROL SYSTEM
	2nd	Classification of Control system
	3rd	Open loop system & Closed loop system and its comparison
	4th	MAHA SHIVA RATRI
	1st	Effects of Feed back
	2nd	Standard test Signals(Step, Ramp, Parabolic, Impulse Functions)
20.02.2023 to	3rd	Servomechanism
	4th	MATHEMATICAL MODEL OF A SYSTEM
25.02.2023	1 - Martin - Frank	Transfer Function & Impulse response.
	5th	Properties, Advantages & Disadvantages of Transfer Function
	1st	Poles & Zeroes of transfer Function
	2nd	Simple problems of transfer function of network.
27.02.2023 to 04.03.2023	3rd	Mathematical modeling of Electrical Systems(R. L. C. Analogous systems)
	4th	CONTROL SYSTEM COMPONENTSComponents of Control System
	5th	Gyroscope, Synchros, Tachometer, DC servomotors, Ac Servomotors.BLOCK DIAGRAM ALGEBRA & SIGNAL FLOW GRAPHS
06.03.2023 to 11.03.2023	1st	Definition: Basic Elements of Block Diagram
	2nd	DOLO PURNIMA
	3rd	HOLI
	4th	Canonical Form of Closed loop Systems
	5th	Rules for Block diagram reduction
13.03.2023 to 18.03.2023	1st	Procedure for of Reduction of Block Diagram
	2nd	Simple Problem for equivalent transfer function
	3rd	Basic Definition in Signal Flow Graph & properties
10.03.2025	4th	Construction of Signal Flow graph from Block diagram
and the second	5th	Mason's Gain formula
20.03.2023	1st	Simple problems in Signal flow graph for network
	2nd	TIME RESPONSE ANALYSIS. Time response of control system.
to	3rd	Standard Test signal.
25.03.2023	4th	Step signal, Ramp Signal, Parabolic Signal, Impulse Signal
	5th	Time Response of first order system with:
	1st	Unit step response

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27.02.2022	20-1	Unit impulse response
27.03.2023	2nd	Time response of second order system to the unit step input.
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01.04.2025	4(1)	RAIVIA NAVAIVII
	5"	UTKAL DIVAS
	1st	Time response specification.
03.04.2023 to 08.04.2023	2nd	Derivation of expression for rise time, peak time, peak oversities,
		settling time and steady state error.
	3rd	Steady state error and error constants.
	4th	Types of control system. [Steady state errors in Type-0, Type =/ The
	5th	Effect of adding poles and zero to transfer function
10.04.2023	1st	Response with P. PI, PD and PID controller.
	2nd	ANALYSIS OF STABILITY BY ROOT LOCUS TECHNIQUE.
	3rd	Root locus concept.
15.04.2023	4th	Construction of root loci.
1510 112020	5th	Rules for construction of the root locus.
7.5.5.5.	1st	Effect of adding poles and zeros to G(s) and H(s).
17.04.2023	2nd	FREQUENCY RESPONSE ANALYSIS.
to	3rd	Correlation between time response and frequency response.
22.04.2023	4th	Polar plots
	5th	ID-UI-FITRE
	1st	Bode plots.
24.04.2023	2nd	All pass and minimum phase system.
to	3rd	Computation of Gain margin and phase margin.
29.04.2023	4th	Computation of Gain margin and phase margin.
	5th	Computation of Gain margin and phase margin.
01.05.2023	1st	Closed loop frequency response.
	2nd	NYQUIST PLOT
	3rd	NYQUIST PLOT
to	4th	Principle of argument.
06.05.2023	5th	Principle of argument.
08.05.2023 to 13.05.2023	1st	Principle of argument.
	2nd	Nyquist stability criterion.
	3rd	Nyquist stability criterion.
	4 th	Niquist stability criterion applied to inverse polar plot.
	5 th	Niquist stability criterion applied to inverse polar plot.
15.05.2023 to 20.05.2023	1st	plot.
	2nd	Effect of addition of poles and zeros to G(S) H(S) on the shape of Niquist
		plot.
	3 rd	Assessment of relative stability.
	4 th	Assessment of relative stability.
	5 th	Constant M and N circle
22.05.2023 to	1 st	Constant M and N circle
	2 nd	Constant M and N circle
	3 rd	Nicholas chart
25.05.2023	4 th	Nicholas chart

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